**PROBABILISTIC REASONING ASSIGNMENTS 1-3**

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1. **What is a Bayesian classifier?**

**LAB-1**

A Bayesian classifier is a type of statistical classifier based on Bayes' Theorem, which provides a way to update the probability of a hypothesis as more evidence becomes available. It’s widely used in machine learning for tasks such as classification, especially with text data. The most well-known example is the Naive Bayes classifier.

1. **Why we use a Naive Bayes Classifier? Why it is called Naive?**

A Naive Bayes classifier is used because it is simple, efficient, and effective for many classification tasks, especially with high-dimensional data like text. Despite its simplicity, it can perform well in various applications such as email spam detection, sentiment analysis, and medical diagnosis.

The classifier is termed "naive" because it makes a naive assumption: it assumes that all features are conditionally independent given the class label.

1. **What are the possible advantages in choosing Naive Bayes Classifier?**
   * Simple and Fast: Easy to implement and quick to train, even on large datasets.
   * Effective with Small Data: Works well with limited training data.
   * Performs Well with High-Dimensional Data: Great for text classification and other tasks with many features.
   * Handles Multi-Class Problems: Naturally supports multi-class classification.
   * Interpretable: Provides clear probability estimates for each class.
   * Robust to Irrelevant Features: Can perform well even with noisy or irrelevant features.
2. **Prepare a classification model using Naive Bayes for the given data.**
3. **Consider class Fish as Y1, class Animal as Y2, and class Bird as Y3 Compute P(Y1), P(Y2), P(Y3).**
4. **Consider the test sample X=(Slow, Rarely, No). Predict the class label for the test sample, using the Naive Bayes classifier. (Hint: Find P(Y1/X), P(Y2/X), and P(Y3/X)).**

[\* Executing Qns 4 to 6 in a single code \*] CODE

% Data preparation

Swim = {'Fast', 'Fast', 'Slow', 'Fast', 'No', 'No', 'No', 'Slow', 'Slow', 'Slow', 'No', 'Fast'}';

Fly = {'No', 'No', 'No', 'No', 'Short', 'Short', 'Rarely', 'No', 'No', 'No', 'Long', 'No'}';

Crawl = {'No', 'Yes', 'No', 'No', 'No', 'No', 'No', 'Yes', 'No', 'Yes', 'No', 'No'}';

ClassLabel = {'Fish', 'Animal', 'Animal', 'Animal', 'Bird', 'Bird', 'Animal', 'Animal', 'Fish', 'Fish', 'Bird', 'Bird'}';

% Convert categorical data into numeric categories\_swim = unique(Swim); categories\_fly = unique(Fly); categories\_crawl = unique(Crawl); categories\_class = unique(ClassLabel);

Swim\_int = arrayfun(@(x) find(strcmp(x, categories\_swim)), Swim); Fly\_int = arrayfun(@(x) find(strcmp(x, categories\_fly)), Fly); Crawl\_int = arrayfun(@(x) find(strcmp(x, categories\_crawl)), Crawl);

ClassLabel\_int = arrayfun(@(x) find(strcmp(x, categories\_class)), ClassLabel);

% Combine data into a matrix

data = [Swim\_int, Fly\_int, Crawl\_int, ClassLabel\_int];

% Step 2: Compute Prior Probabilities P(Y1), P(Y2), P(Y3)

num\_classes = length(categories\_class);

priors = histc(data(:, end), 1:num\_classes) / size(data, 1); disp('Prior Probabilities:');

for c = 1:num\_classes

fprintf('P(Y%d) = %.2f\n', c, priors(c)); end

% Step 3: Calculate likelihoods P(X|Y) for each feature and class num\_features = size(data, 2) - 1;

likelihoods = cell(num\_classes, num\_features); for c = 1:num\_classes

class\_data = data(data(:, end) == c, 1:num\_features); for f = 1:num\_features

feature\_vals = unique(data(:, f));

likelihoods{c, f} = histc(class\_data(:, f), feature\_vals) / size(class\_data, 1); end

end

% Test sample X = (Slow, Rarely, No)

test\_sample = [find(strcmp('Slow', categories\_swim)), ... find(strcmp('Rarely', categories\_fly)), ... find(strcmp('No', categories\_crawl))];

% Step 4: Compute posterior probabilities P(Y|X) = P(X|Y)\*P(Y)/P(X) posteriors = zeros(num\_classes, 1);

for c = 1:num\_classes posterior = priors(c); for f = 1:num\_features

posterior = posterior \* likelihoods{c, f}(test\_sample(f)); end

posteriors(c) = posterior; end

% Normalize posteriors to get P(Y1|X), P(Y2|X), P(Y3|X) posteriors = posteriors / sum(posteriors);

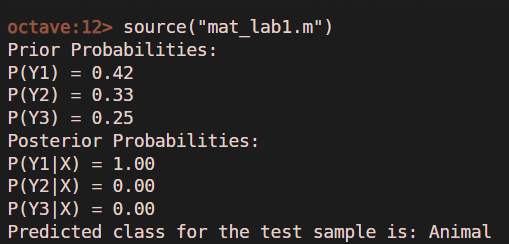
% Display results disp('Posterior Probabilities:'); for c = 1:num\_classes

fprintf('P(Y%d|X) = %.2f\n', c, posteriors(c)); end

% Predict the class label

[~, predicted\_class\_idx] = max(posteriors); predicted\_class = categories\_class{predicted\_class\_idx};

fprintf('Predicted class for the test sample is: %s\n', predicted\_class);



# LAB-2

# Install the required library

!pip install pgmpy



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# Install pgmpy and supporting libraries

!pip install pgmpy networkx matplotlib

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from pgmpy.models import BayesianNetwork

# Step 1: Define the Bayesian Network structure model = BayesianNetwork([

('Diff', 'Grade'), # Difficulty influences Grade ('Intel', 'Grade'), # Intelligence influences Grade ('Grade', 'Letter'),# Grade influences Letter

('Intel', 'SAT')]) # Intelligence influences SAT

# Step 2: Define the CPDs (Conditional Probability Distributions) from pgmpy.factors.discrete import TabularCPD

# CPD for Difficulty

cpd\_diff = TabularCPD(variable='Diff', variable\_card=2,

values=[[0.6], [0.4]],

state\_names={'Diff': ['Easy', 'Hard']})

# CPD for Intelligence

cpd\_intel = TabularCPD(variable='Intel', variable\_card=2,

values=[[0.7], [0.3]],

state\_names={'Intel': ['Dumb', 'Intelligent']})

# CPD for Grade

cpd\_grade = TabularCPD(variable='Grade', variable\_card=3,

values=[

[0.3, 0.05, 0.9, 0.5], # Grade A (G=0)

[0.4, 0.25, 0.08, 0.3], # Grade B (G=1)

[0.3, 0.7, 0.02, 0.2] # Grade C (G=2)

],

evidence=['Intel', 'Diff'], evidence\_card=[2, 2],

state\_names={'Grade': ['A', 'B', 'C'], 'Intel': ['Dumb', 'Intelligent'], 'Diff': ['Easy', 'Hard']})

# CPD for SAT

cpd\_sat = TabularCPD(variable='SAT', variable\_card=2,

values=[

[0.95, 0.2], # SAT Bad (S=0)

[0.05, 0.8] # SAT Good (S=1)

],

evidence=['Intel'], evidence\_card=[2],

state\_names={'SAT': ['Bad', 'Good'], 'Intel': ['Dumb', 'Intelligent']})

# CPD for Letter

cpd\_letter = TabularCPD(variable='Letter', variable\_card=2,

values=[

[0.1, 0.4, 0.99], # Letter Bad (L=0)

[0.9, 0.6, 0.01] # Letter Good (L=1)

# Add CPDs to the model

],

evidence=['Grade'], evidence\_card=[3],

state\_names={'Letter': ['Bad', 'Good'], 'Grade': ['A', 'B', 'C']})

model.add\_cpds(cpd\_diff, cpd\_intel, cpd\_grade, cpd\_sat, cpd\_letter)

# Validate the model

assert model.check\_model()

print("CPDs:") print(cpd\_diff) print(cpd\_intel) print(cpd\_grade) print(cpd\_sat)

print(cpd\_letter)

 CPDs:

+------------+-----+

| Diff(Easy) | 0.6 |

+------------+-----+

| Diff(Hard) | 0.4 |

+------------+-----+

+--------------------+-----+

| Intel(Dumb) | 0.7 |

+--------------------+-----+

| Intel(Intelligent) | 0.3 |

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| Intel | Intel(Dumb) | Intel(Dumb) | Intel(Intelligent) | Intel(Intelligent) |

+----------+-------------+-------------+--------------------+--------------------+

| Diff | Diff(Easy) | Diff(Hard) | Diff(Easy) | Diff(Hard) |

+----------+-------------+-------------+--------------------+--------------------+

| Grade(A) | 0.3 | 0.05 | 0.9 | 0.5 |

+----------+-------------+-------------+--------------------+--------------------+

| Grade(B) | 0.4 | 0.25 | 0.08 | 0.3 |

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| Grade(C) | 0.3 | 0.7 | 0.02 | 0.2 |

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| Intel | Intel(Dumb) | Intel(Intelligent) |

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| SAT(Bad) | 0.95 | 0.2 |

+-----------+-------------+--------------------+

| SAT(Good) | 0.05 | 0.8 |

+-----------+-------------+--------------------+

+--------------+----------+----------+----------+

| Grade | Grade(A) | Grade(B) | Grade(C) |

+--------------+----------+----------+----------+

| Letter(Bad) | 0.1 | 0.4 | 0.99 |

+--------------+----------+----------+----------+

| Letter(Good) | 0.9 | 0.6 | 0.01 |

+--------------+----------+----------+----------+

# Step 3: Local independencies and active trail nodes # Local Independencies

print("Local Independencies:")

print(model.local\_independencies('Diff')) print(model.local\_independencies('Intel')) print(model.local\_independencies('Grade')) print(model.local\_independencies('SAT'))

print(model.local\_independencies('Letter'))

# Active trail nodes for 'Diff'

print("\nActive trail nodes for 'Diff':") print(model.active\_trail\_nodes('Diff'))

 Local Independencies: (Diff ⟂ SAT, Intel) (Intel ⟂ Diff)

(Grade ⟂ SAT | Diff, Intel)

(SAT ⟂ Diff, Grade, Letter | Intel) (Letter ⟂ SAT, Diff, Intel | Grade)

Active trail nodes for 'Diff':

{'Diff': {'Diff', 'Grade', 'Letter'}}

# Step 4: Visualize the Bayesian Network import networkx as nx

import matplotlib.pyplot as plt

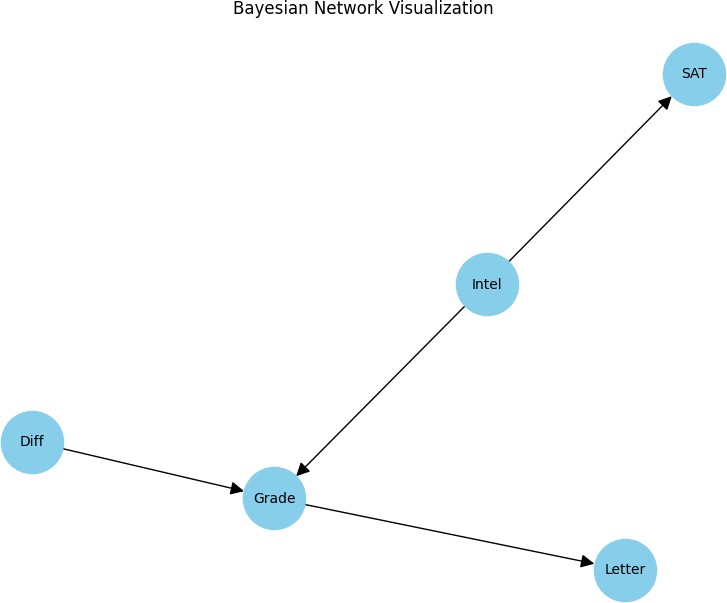
# Manually convert the BayesianNetwork into a networkx graph graph = nx.DiGraph() # Directed graph for Bayesian networks for edge in model.edges():

graph.add\_edge(edge[0], edge[1])

# Visualize the graph using networkx plt.figure(figsize=(8, 6))

nx.draw(graph, with\_labels=True, node\_color="skyblue", font\_size=10, node\_size=2000, edge\_color="black", arrowsize=20) plt.title("Bayesian Network Visualization")

plt.show()



import networkx as nx

import matplotlib.pyplot as plt

# Create a directed graph using networkx graph = nx.DiGraph()

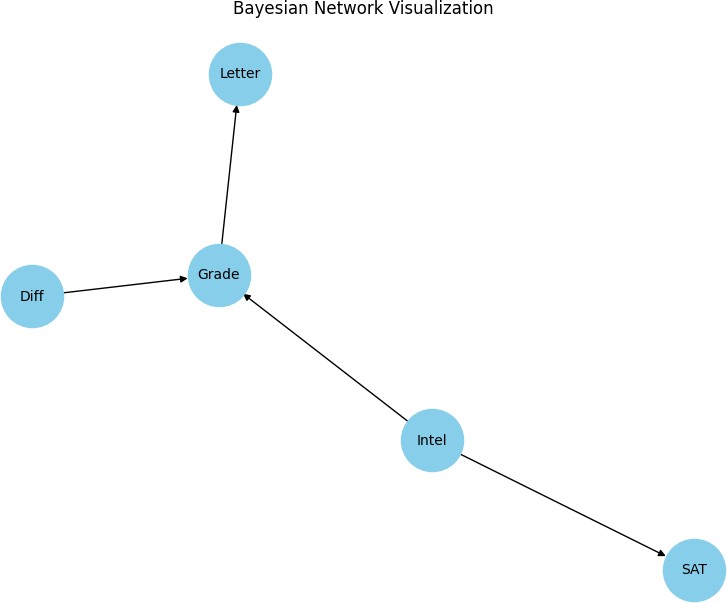
# Add nodes and edges from the Bayesian Network graph.add\_nodes\_from(model.nodes())

graph.add\_edges\_from(model.edges())

# Visualize the graph using networkx plt.figure(figsize=(8, 6))

nx.draw(graph, with\_labels=True, node\_color="skyblue", font\_size=10, node\_size=2000, edge\_color="black") plt.title("Bayesian Network Visualization")

plt.show()

# LAB-3

 ASHWIN SASI

AM.EN.U4AIE22007

# Install the pgmpy library

!pip install pgmpy

 Collecting pgmpy

Downloading pgmpy-0.1.26-py3-none-any.whl.metadata (9.1 kB)

Requirement already satisfied: networkx in /usr/local/lib/python3.10/dist-packages (from pgmpy) (3.4.2) Requirement already satisfied: numpy in /usr/local/lib/python3.10/dist-packages (from pgmpy) (1.26.4)

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Requirement already satisfied: pydantic in /usr/local/lib/python3.10/dist-packages (from google-generativeai->pgmpy) (2.10.3)

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Requirement already satisfied: tzdata>=2022.7 in /usr/local/lib/python3.10/dist-packages (from pandas->pgmpy) (2024.2)

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# Import necessary modules

from pgmpy.models import MarkovNetwork

from pgmpy.factors.discrete import DiscreteFactor from pgmpy.inference import VariableElimination

# Step 1: Define the Markov Network # Create an empty Markov Network

model = MarkovNetwork()

# Add edges as per the network structure from the table

model.add\_edges\_from([('A', 'B'), ('B', 'C'), ('C', 'D'), ('D', 'A')])

# Step 2: Add the Factors # Factor φ(A, B)

phi\_AB = DiscreteFactor( variables=['A', 'B'],

cardinality=[2, 2], # Binary variables values=[

[30, 5], # A=0, B=0 | A=0, B=1 [1, 10] # A=1, B=0 | A=1, B=1

]

)

# Factor φ(B, C)

phi\_BC = DiscreteFactor( variables=['B', 'C'], cardinality=[2, 2], values=[

[100, 1], # B=0, C=0 | B=0, C=1 [1, 100] # B=1, C=0 | B=1, C=1

]

)

# Factor φ(C, D)

phi\_CD = DiscreteFactor( variables=['C', 'D'], cardinality=[2, 2], values=[

[1, 100], # C=0, D=0 | C=0, D=1 [100, 1] # C=1, D=0 | C=1, D=1

]

)

# Factor φ(D, A)

phi\_DA = DiscreteFactor( variables=['D', 'A'], cardinality=[2, 2], values=[

[100, 1], # D=0, A=0 | D=0, A=1 [1, 100] # D=1, A=0 | D=1, A=1

]

)

# Add these factors to the model

model.add\_factors(phi\_AB, phi\_BC, phi\_CD, phi\_DA)

# Step 3: Perform inference

inference = VariableElimination(model)

# Example query: MAP estimation for variable 'C' given evidence A=0 and B=1 result = inference.map\_query(variables=['C'], evidence={'A': 0, 'B': 1})

print("\nMAP Query result (C given A=0, B=1):") print(result)

# Example query: Probability of 'C' given evidence

prob\_result = inference.query(variables=['C'], evidence={'A': 0, 'B': 1}) print("\nProbability distribution of 'C' given A=0, B=1:")

print(prob\_result)

Eliminating: D: 100% 1/1 [00:00<00:00, 63.14it/s]

MAP Query result (C given A=0, B=1):

{'C': 1}

Probability distribution of 'C' given A=0, B=1:

+------+--------------+

| C | phi(C) |

+======+==============+

| C(0) | 1000.0000 |

+------+--------------+

| C(1) | 5000500.0000 |

+------+--------------+